

Modelling Ecological Populations

Game Theory Project

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Dynamic Games : Theory and Applications IIT Madras

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Reinforcement Learning

- Provides a formalism for behavior
- Obtained from behavioral psychology
- Helpful for modelling ecological populations

Figure: Reinforcement Learning

Methods in Reinforcement Learning

Policy Gradient

- Players have policies (actions)
- Optimize in the policy space
- Gradient Ascent
- **Episodic reward**
- $\pi(a_i, \theta)$ = Policy parameterized by θ .

 θ represents the parameters of our neural network.

$$
\Delta \theta = \alpha_t r_r \frac{d}{d\theta} \pi(a_t, \theta_t)
$$

- Multi-Armed Bandits
	- \blacksquare Players pick from k arms
	- \blacksquare Find the best arm to pull

- What is it?
	- **Models interaction within same species**
	- Sharing of resources
- \blacksquare Pay-off matrix :

 $B < C$; (B=6, C=10 in our expts)

The pay-off of player i is denoted by $u_i(s_i, s_j)$

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Nash Equilibria : Hawk-Dove Game

- 3 nash equilibria
- 2 pure + 1 mixed $\mathcal{L}_{\mathcal{A}}$

Figure: Nash Equilibria in a Hawk-Dove Game[\[2\]](#page-39-1)

- A population of N players
- Each player can be a hawk or a dove T.
- Pay-off decided based on interaction with population
- Pay-off of player i in the population is denoted by $u_i(s_i, s_{-i})$ m.

Figure: N-player hawk-dove game

From RL Perspective

Figure: N-player hawk-dove game (Ref : [MARL\)](https://towardsdatascience.com/modern-game-theory-and-multi-agent-reinforcement-learning-systems-e8c936d6de42)

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 \blacksquare Playing against the field

$$
u_i(s_i, s_{-i}) = \frac{1}{N} \sum_{\forall j \neq i} u_i(s_i, s_j)
$$

² Playing against a group *M^j*

$$
u_i(s_i, s_{-i}) = \frac{1}{|M_j|} \sum_{j \in M_j} u_i(s_i, s_j)
$$

3 Pair-wise contest (Player j chosen randomly by nature)

$$
u_i(s_i, s_{-i}) = u_i(s_i, s_j)
$$

A better understanding of its significance during convergence

Figure: Convergence comparison of the three methods of calculating individual payoffs : Playing against the field, Playing against a group and Pair-wise contest respectively

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- **Static Games:** A static game is one in which all players make decisions (or select a strategy) simultaneously, without knowledge of the strategies that are being chosen by other players. Even though the decisions may be made at different points in time, the game is simultaneous because each player has no information about the decisions of others; thus, it is as if the decisions are made simultaneously.
- **Stage Games**: A Stage Game is a game that arises in certain stage of a static game. In other words, the rules of the games depend on the specific stage. The prisoner's dilemma is a classic example of stage game

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- Selfish agents
- Policy Gradient update
- Players have stochastic strategies, but play pure strategies

Figure: RL mechanism for pairwise contests

Players are matched randomly

2 Strategies drawn from Bernoulli distribution

Figure: State of population over time: pairwise contests

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- ¹ Strategies drawn from Bernoulli distribution
- 2 Payoff obtained against population profile
- ³ Population converges faster (sort of)

Figure: State of population over time: against the field

- Players still selfish...
- But agree to a "code of conduct" or Rules of Engagement (RoE)
- Code of conduct updated by each player in turns T.

Figure: Depiction of a game with code of conduct

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- Parameterized function $\mathcal{L}_{\mathcal{A}}$
- Can be tweaked by players m.

Figure: Example neural network

Players are matched one on one randomly by Nature 2 Players update RoE and display state through experience

Figure: State of population (RoE) over time: pairwise contests. Some amount of inherent forced cooperation observed resulting in a population pay-off higher than MSNE

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- Again, final population profile not MSNE.
- Lower variance during steady state.

Figure: State of population (RoE) over time: against field. Some amount of inherent forced cooperation observed resulting in a population pay-off higher than MSNE

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A person must choose between multiple actions (originally comes from the idea of slot machines, the "one-armed bandits"), each with an unknown reward.

Figure: Multi-Armed Bandit Problem

- Goal : determine the best or most profitable outcome through a series of choices.
- At the beginning of the experiment, when odds and payouts are unknown, the gambler must determine which machine to pull, in which order and how many times.

Upper Confidence Bound Algorithm : (For a single player)

> Initialization: Play each arm once, **For** $t = K + 1, ..., n$, **repeat** (1) Play arm $I_t = argmax_{k=1,...,K} UCB_t(k)$, where $\mathsf{UCB}_t(k) = \hat{\mu}_k(t-1) + \sqrt{\frac{8\log t}{T_k(t-1)}}$ (2) Observe sample X_t from the distribution P_t corresponding to the arm *I^t* .

Figure: Evolution of Population over time and the average pay-off of the population over time when the population is initialized randomly with probability 0.5 (Equivalent to individual pay-off over time after convergence in this case). **Each player interacts with everyone else in the population.**

Playing against Field

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Playing Against a Group

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Pair-wise contest

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Summarizing UCB experiments

Observations :

- In all 3 cases, the population converges to a cycle (either all Hawk or all Dove)
- In all 3 cases, the average population pay-off converges to a cycle (either -2 or $+3$)
- The convergence rate of the 3 methods similar to Full Batch GD, Mini Batch GD and SGD
- Inference :
	- Playing against Field : When majority of the **current** population is Dove(>40%), better to be a Hawk.
	- Playing Against a Group : When majority of the **sampled** population is Dove(>40%), better to be a Hawk
	- **Pair-wise contest : When he's a Dove, I'm better off as Hawk**
- Reason :
	- **Each player in each iteration chooses best response**

Group Play

Figure: Evolution of Population over time and the average pay-off of the population over time when the population is initialized randomly with probability 0.5. **A group of m=10**% **of the population interacts in each interaction.**

Group Play

Figure: Evolution of Population over time and the average pay-off of the population over time when the population is initialized randomly with probability 0.5. **A group of m=10**% **of the population interacts in each interaction.**

Observation :

Fairly robust to different population initialization techniques :

 \blacksquare Average population pay-off better than MSNE pay-off

The State Reason :

 \blacksquare The change in population distribution is minimal

[Future Work](#page-33-0)

- Asymmetric Games (eg) Trust-Cooperate
- Strange attractors to analyse chaotic populations
- Quantifying rewards of cooperation
- Informed Reinforcement learners : use communication through revelation schemes

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Axelrod - Evolution of Cooperation

- Also used to analyze behavior of populations m.
- made use of evolutionary programming

Figure: 5 stages of the evolution of cooperation

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Evolutionary Game Theory and Multi-Agent Reinforcement Learning

- Authors : Karl Tuyls and Ann Nowe
- Survey the basics of RL and (Evolutionary) Game Theory
- Multi-Agent Systems
- Mathematical connection between MARL and Evolutionary Game Theory
- Ref : **[Paper pdf](https://pdfs.semanticscholar.org/bb9f/bee22eae2b47bbf304804a6ac07def1aecdb.pdf)**

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THANK YOU :)

